

The 14th U.S.-Korea Forum on Nanotechnology:
Internet of Things (IoT) including Nanosensors and
Neuromorphic Computing

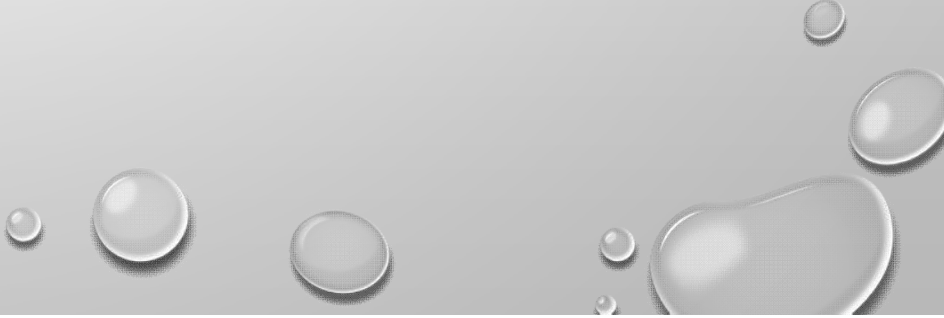
SENSOR DEVICES FOR REMOTE SENSING

DONG KYOO KIM

2017.9.11



CONTENTS

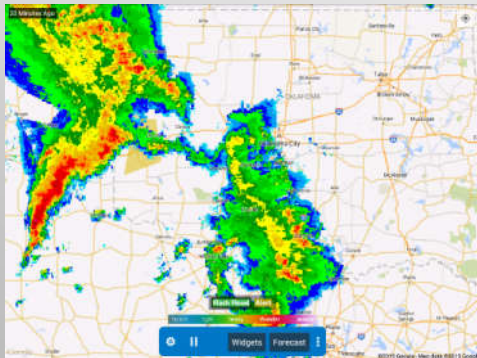
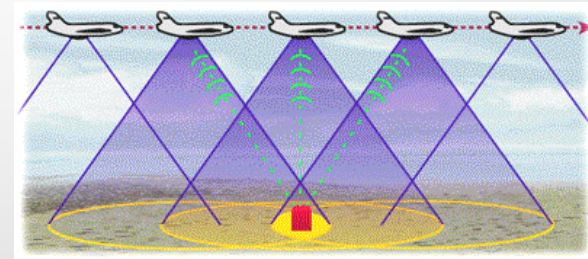
1. RADAR FOR REMOTE SENSING
 2. PENETRATION RADAR
 3. BIO RADAR
 4. GESTURE RADAR
 5. CONCLUSIONS
- 

The background of the slide is a light gray gradient with several realistic water droplets of various sizes scattered across it. Some droplets are in the top left corner, some are in the bottom right, and others are in the lower middle. The droplets have highlights and shadows, giving them a three-dimensional appearance.

1. RADAR FOR REMOTE SENSING

REMOTE SENSING

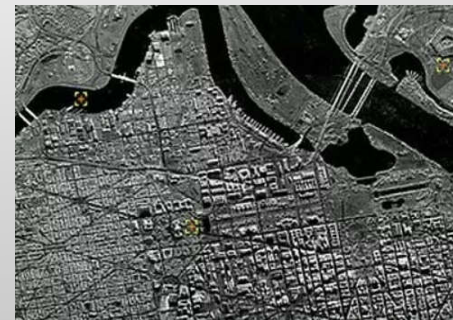
- DEFINITION(WIKI): THE ACQUISITION OF INFORMATION ABOUT AN OBJECT OR PHENOMENON WITHOUT MAKING PHYSICAL CONTACT WITH THE OBJECT
- EXAMPLES: WEATHER RADAR, AIRBORNE RADIO MAP RADAR
- USUALLY INDUSTRIAL OR MILITARY PRODUCT



google play store



wikipedia



www.quora.com

Rain droplet tracking, Thunderstorm tracking

Earth surface Imaging

REMOTE SENSING TO OUR LIFE

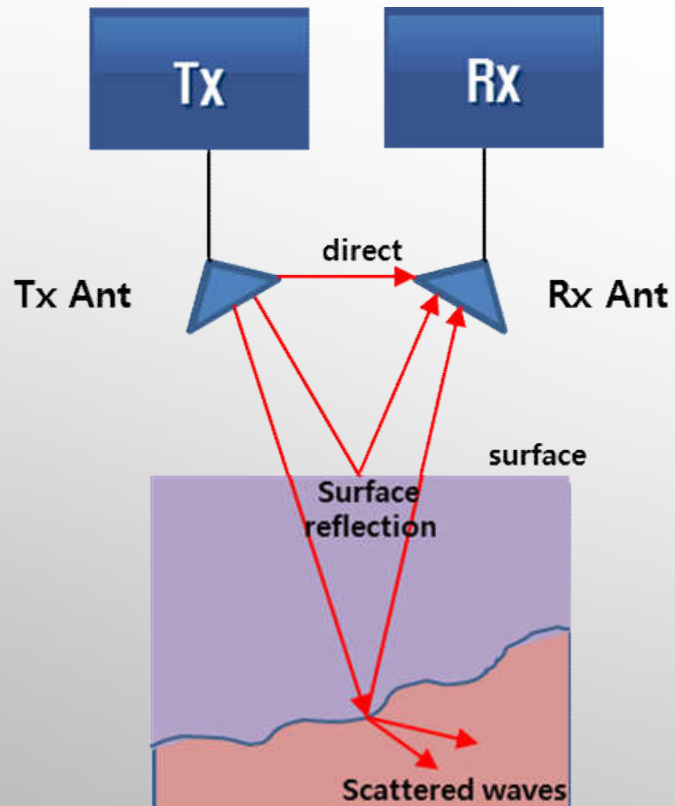
- REMOTE SENSING TECHNOLOGY COMES TO OUR LIFE
- MILITARY, INDUSTRIAL DEVICE TO CONSUMER ELECTRONIC DEVICE
- BIG SYSTEM TO SMALL SIZED MODULE
- RESEARCH AREA: PENETRATION, BIO, GESTURE RADAR



The background of the slide is a light gray gradient. It is decorated with several realistic water droplets of various sizes and shapes, some appearing to be on a surface and others floating. The droplets are rendered with soft shadows and highlights, giving them a three-dimensional appearance. They are scattered across the page, with a cluster in the top left, a few in the middle left, and a larger group in the bottom right.

2. PENETRATION RADAR

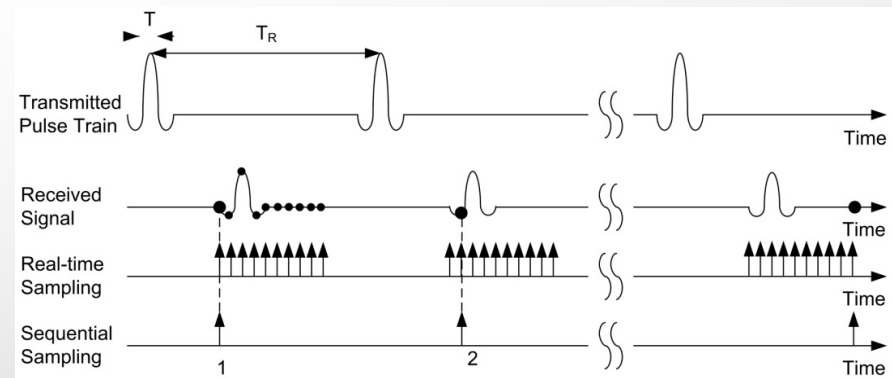
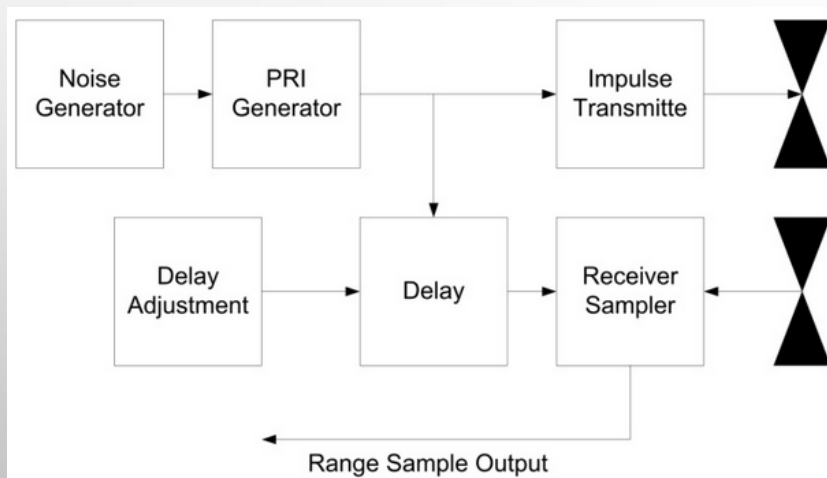
GROUND PENETRATION RADAR (GPR)



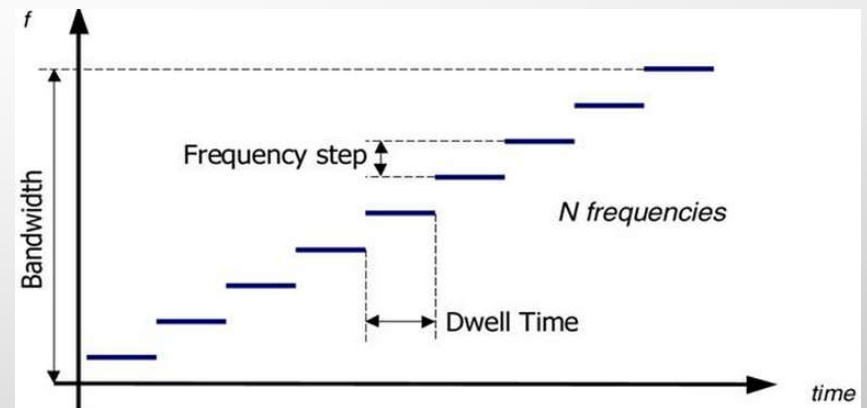
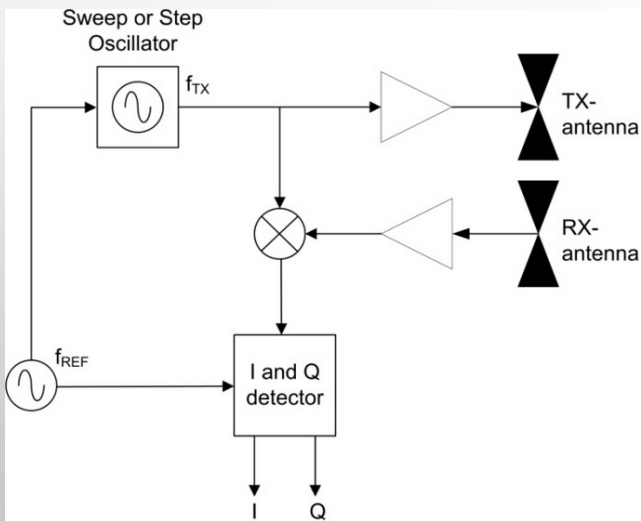
- TRANSMIT ELECTROMAGNETIC WAVES.
- BOUNDARIES WITH DIFFERENT MATERIALS REFLECT WAVES.
- PENETRATION IMAGE CAN BE OBTAINED BY THE REFLECTED WAVES.



IMPULSE GPR



STEP-FREQUENCY GPR

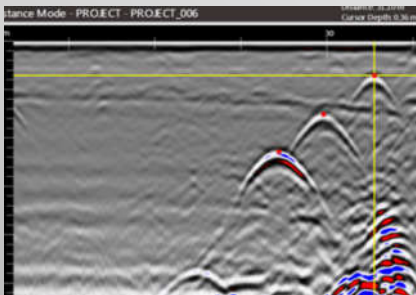


TIME-DOMAIN REFLECTED WAVE IMAGING

Radar signal
transmission

Signal Record

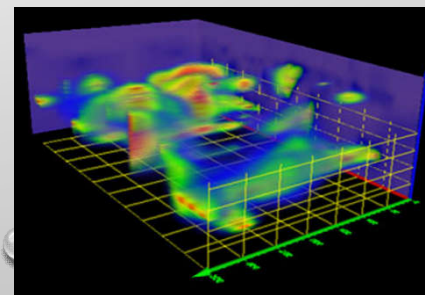
Reflected Wave
Image



Background Noise
reduction,
Clutter removal

Focusing, migration

Visualization

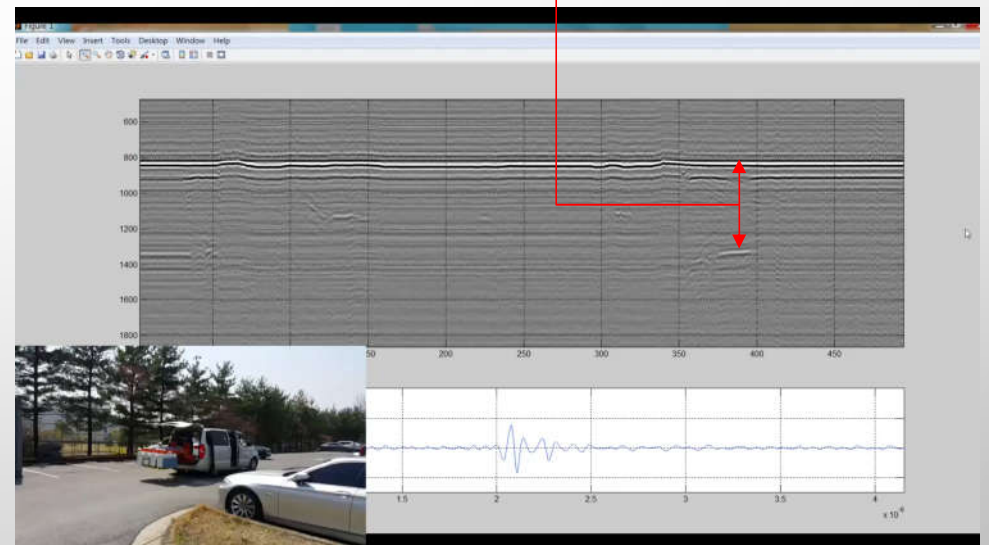


GROUND PENETRATION TEST

time: 13nsec

distance: 1.12m(@ $\epsilon_r=3$)

- PAVED ROAD PENETRATION
- FREQ: 400MHZ ~ 4.5GHZ
- BIG ARRAY ANTENNA



LOCALIZING GPR (LGPR)

- LGPR COMPLEMENTS EXISTING VISION-BASED AUTONOMOUS VEHICLE TECHNOLOGIES
- WORKS WELL IN ALL WEATHER CONDITIONS, DAY AND NIGHT
- REAL-TIME ARRAYED TD RW IMAGING

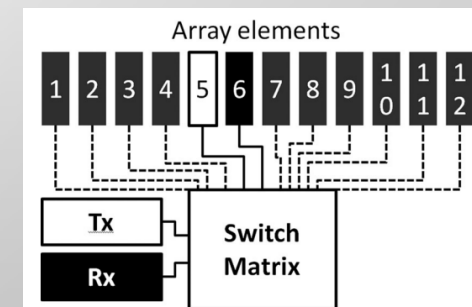


Road surface change



- Freq: 100M~400MHz
- Method: Step-Frequency
- Spacing: 6MHz

- Array: 12 antennas
- TRX: 11 channels



TERAHERTZ PENETRATION IMAGING

- Terahertz: submillimeter radiation
- ITU-designated band: 0.3~3THz
- High resolution due to high bandwidth
- Thin surface penetration



Penetration Camera

- Freq: 50GHz~0.7THz
- Resolution: 1 mm
- High speed: 5000 fps



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3. BIO RADAR

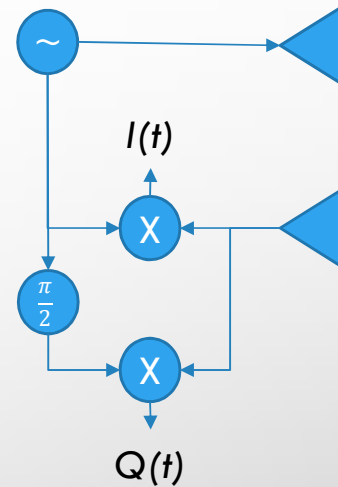
MICRO-DOPPLER RADAR

- SMALL ANGLE APPROXIMATION

$$\begin{aligned}
 S(t) &= I(t) + j \cdot Q(t) = \exp \left\{ j \left[\frac{4\pi x_h(t)}{\lambda} + \frac{4\pi x_r(t)}{\lambda} + \phi \right] \right\} \\
 &= 2j \left[C_{10} \sin(\omega_r t) + C_{01} \sin(\omega_h t) + \dots \right] \cdot e^{j\phi} \\
 &\quad + 2 \left[C_{20} \cos(2\omega_r t) + C_{02} \cos(2\omega_h t) + \dots \right] \cdot e^{j\phi}
 \end{aligned}$$

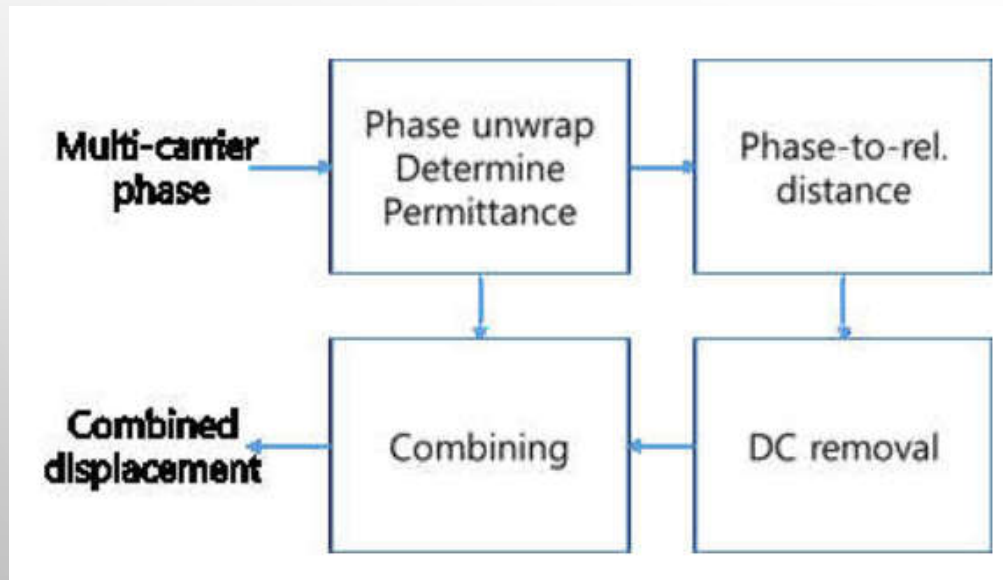
- ARC-TANGENT DEMODULATION

$$\phi'(t) = \arctan \left(\frac{B_Q(t)}{B_I(t)} \right) = \arctan \left(\frac{V_Q + A_r \sin(\theta + 4\pi\Delta x(t)/\lambda)}{V_I + A_r \cos(\theta + 4\pi\Delta x(t)/\lambda)} \right)$$



Doppler radar

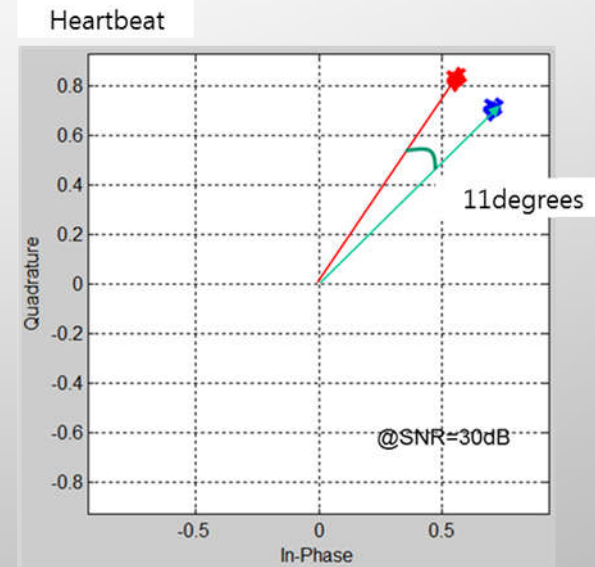
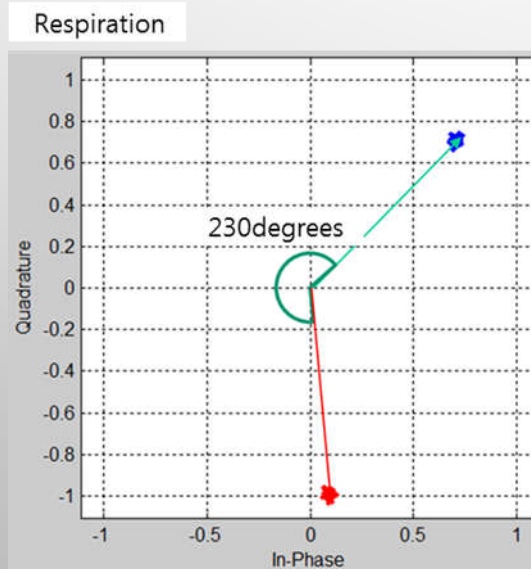
METHOD



Permittance checklist
Displacement of the checked
sub-carriers are only combined.

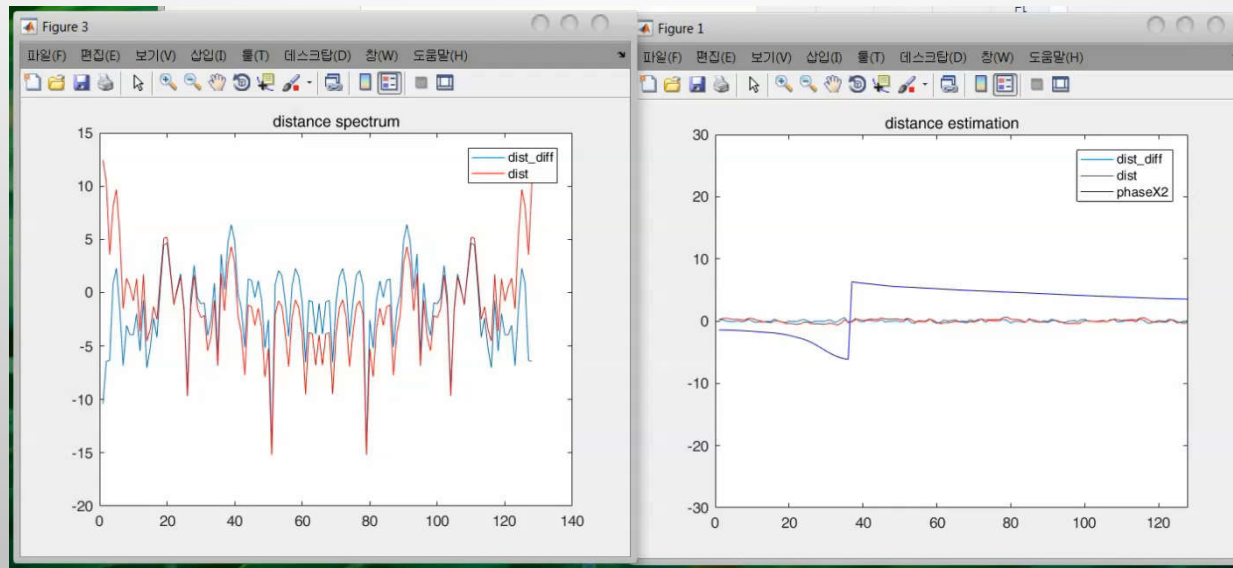
DISPLACEMENT OF BIOLOGICAL SIGNAL

- PHASE SHIFT BY CHEST MOVEMENT OF RESPIRATION AND HEARTBEAT IS DIFFERENT.
- RESPIRATION MAKES 230 DEGREES OF DOPPLER PHASE SHIFT.
- HEARTBEAT MAKES 11 DEGREES OF DOPPLER PHASE SHIFT.



EXAMPLE

- HEARTBEAT SIGNAL CAN BE DETECTED BY 24GHZ MICRO-DOPPLER RADAR
- HEARTBEAT SIGNAL: BLUE LINE



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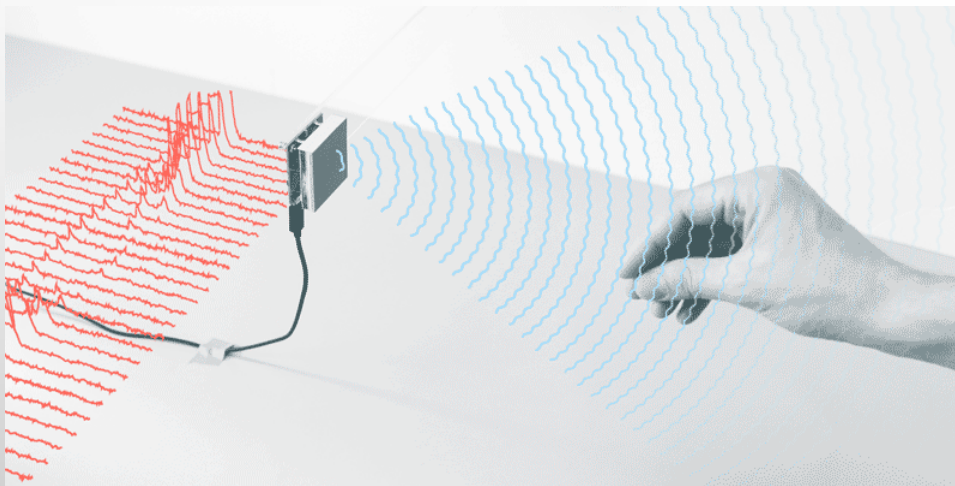
4. GESTURE RADAR

WORLD'S SMALLEST VIOLIN

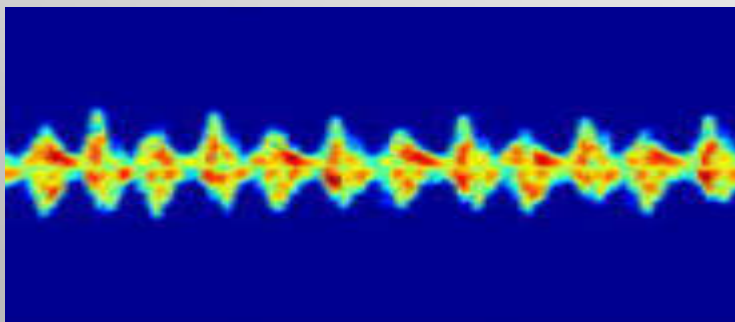


World's Smallest Violin – Google's Project Soli (Youtube)

GESTURE RADAR



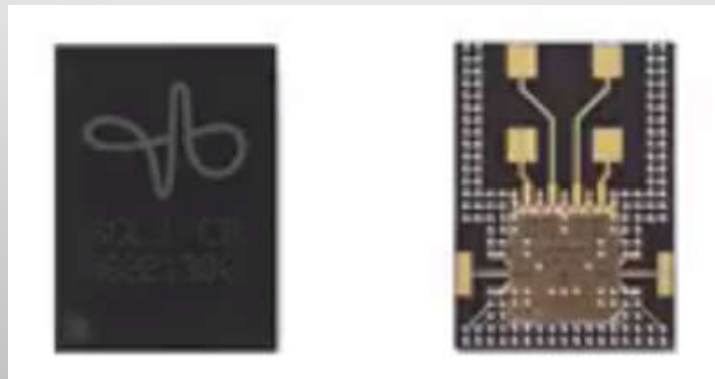
- EMITS ELECTROMAGNETIC WAVES.
- HAND REFLECTS THIS WAVE ENERGY.
- CAPTURES ENERGY, TIME DELAY, AND FREQUENCY SHIFT.
- ESTIMATES HAND DYNAMICS.
- DETERMINES GESTURES.



Micro-Doppler signature

BEING SMALLER

- 8MM X 10MM CHIP WITH RADAR TECHNOLOGY THAT USES GESTURE CONTROLS TO MAKE DEVICES TOUCHLESS.
- 7GHZ MAKES 140PSEC PULSE WAVE.
- FOUR ANTENNAS ARE PLACED TO ACQUIRE AOA INFORMATION.
- BEING TESTED FOR WATCH AND SPEAKER.



CONCLUSIONS

- THREE EMERGING RADAR TECHNOLOGY: PENETRATION, BIO, GESTURE
- TECHNICAL ISSUES
 - ARRAY ANTENNA SIZE REDUCTION FOR HIGH QUALITY PENETRATION IMAGING.
 - DETECTION RELIABILITY AGAINST MOTION ARTIFACT FOR BIO RADAR.
 - REAL-TIME ALGORITHM FOR GESTURE RADAR FOCUSING ALGORITHM (RMA,RDA.)
 - TRANSCEIVER ARCHITECTURE, DENSE ARRAY SIGNAL PROCESSING WHEN FREQUENCY CHANGES FROM GHZ TO THZ.

Thank you